# Assessment of the movement of the car along the sorting slide with a tailwind in the context of environmental health 

Shukhrat Saidivaliev ${ }^{1 *}$, Samandar Sattorov ${ }^{1}$, and Diyora Juraeva ${ }^{1}$<br>${ }^{1}$ Tashkent State Transport University, 100069 Tashkent, Uzbekistan


#### Abstract

In the article, the results of tabular data of previously performed studies of the movement of the car along the descent part of the sorting hump - from its top to the calculated point when exposed to a tailwind of small magnitude are presented in a convenient way for constructing graphical dependencies. For the first time, graphical dependences of acceleration, travel time and rolling speed of the car on the length of the descent part of the hump are constructed.


## 1 Introduction

This article is a continuation of a series of publications on the dynamics of rolling a car down the descent part of the sorting hump when exposed to the projection of a small tailwind force in a simplified formulation of the problem [1-20]. It is known [19] that the descent part of the sorting hump, starting from its top (TH) and ending up to the design point (DP), consists of nine sections without taking into account the installation zone of the brake shoes of the sorting park. These sections are usually called: the first and second high-speed sections (HS1 and HS2), the first braking position (1BP), the intermediate section (IS), the second braking position (2BP), the switch zone (SZ), the first section of the sorting track (ST1), the park mechanized braking position (3BP), the second section sorting track (ST2), the area of installation of brake shoes of the sorting park (ZBSh). Each of the sections of the sorting hump are interconnected by a fracture point of the hump profile [15]. There are different conditions of carriage movement on these sections. For this reason, the force ratios that take place in the "wagon-way" system on each of the sections of the hump are different [1-16]. At each section of the sorting hump, the car rolls down with different linear accelerations $a_{k}$ in magnitude ( k - numbers of the sections of the hump) and, accordingly, in them the travel time $t_{k}$ and the rolling speed of the car $v_{e k}\left(t_{k}\right)$, are different in magnitude, which are determined according to the basic law of dynamics with imperfect coupling [20] in MathCAD. Note that the applied problem of studying the movement of a car from one section of the hump to another is solved by assuming that the rolling speed of the car at the end of one section $v_{e k}$ is equal to the initial one for another section in the form of $v_{0 k}(\mathrm{k}$ - number of the investigated section) [14-16].

[^0]Nevertheless, until now, the results of studies of the movement of the car along the descent part of the sorting hump when exposed to the projection of a small tailwind force are not presented in the form of graphical dependencies of linear acceleration $a_{k}\left(l_{j}\right)$, travel time $t_{k}\left(l_{j}\right)$ and the rolling speed of the car $v_{e k}\left(l_{j}\right)$ along the length of the descent part $l_{j}(j$ - length of each section of the hump corresponding to the number of the investigated section $k$ ). The results of such studies are scientific and practical interest to researchers and design engineers of the sorting hump, therefore they are relevant in the railway transport industry.

## 2 Materials and methods

Using tabular data [16], to construct graphical dependences of linear acceleration, travel time and rolling speed of the car along the length of the descent part of the sorting hump and to perform a generalizing analysis of the research results.

It is required to provide tabular data in [16] in a form convenient for constructing graphical dependencies of linear acceleration $a_{k}\left(l_{j}\right)$, travel time $t_{k}\left(l_{j}\right)$ and rolling speed of the wagon $v_{e k}\left(l_{j}\right)$ along the length of the descent part of the sorting hump $l_{j}(j$ - length of each section of the hump corresponding to the number of the investigated section $k$ ) when exposed to projections of the force of a tailwind of small magnitude on the end side of the car $F_{r \mathrm{rx}}$, taking into account the strength of resistances of all kinds (from the medium, arrows, curve and snow and frost) $F_{\mathrm{c}}$

## 3 Presentation of research results in graphical form and their analysis

To represent tabular data [16] in graphical form, the length of each section $l_{j}$ and the passage time of the $t_{k}$ car in these sections should be presented taking into account the length $l_{j-1}$ and the travel time of the $t_{k-1}$ car of the previous section of the hump.

Below we will explain the values of acceleration $a_{1}$, travel time $t_{1}$ and rolling speed $v_{1}$ obtained for each section of the descent part of the sorting hump and given in Table 1 for the case of exposure to the projection of a tailwind of small magnitude $F_{r \mathrm{rx}}$, taking into account the strength of the resistances of the medium of all kinds (medium, arrows, curves, snow and frost) $F_{\mathrm{c}}$.

1. The first high-speed section (HS1) of the hump with a length of $l_{\text {hsl }}=39.95 \mathrm{~m}$. The slope of the hump is $\psi_{01}=0.05 \mathrm{rad}$. ( 50 ppm ). On HS1, the acceleration of the car $a_{1}=0.519$ $\mathrm{mps}^{2}$, the time of passage by the car of this section $t_{1}=9.558 \mathrm{~s}$ and the speed of its rolling $v_{1}=6.659 \mathrm{mps}$ or 23.97 kmph . For comparison, when exposed to a headwind projection, these data are as follows: $a_{1}=0,445 \mathrm{mps}^{2}$, travel time $t_{1}=10.113 \mathrm{~s}$ and rolling speed $v_{1}$ $=6.2 \mathrm{mps}$ or 22.3 kmph [15]. As can be seen, when exposed to the projection of a tailwind on the car, the acceleration is greater ( $a_{1 \mathrm{t}}>a_{1 \mathrm{~h}}$, where the index 1 t means a tailwind, and 1 h means a headwind), the travel time is less ( $t_{\mathrm{lt}}<t_{\mathrm{lh}}$ ), and the rolling speed is greater ( $v_{1 \mathrm{t}}$ $>v_{\mathrm{lh}}$ ). Similar results can be observed on other sections of the hump, so in the future we will omit such comparisons.
2. The second high-speed section (HS2) of the hump with a length of $l_{\mathrm{hs} 2}=33.63 \mathrm{~m}$ (in Table 1: 73.59 m ). The slope of the hump is $\psi_{02}=0.03 \mathrm{rad}$. $(30 \mathrm{ppm})$. Here we consider the movement of the car in two stages: before and after the switch (arrows).
2.1. The speed of the entrance of the car (initial speed) on the HS2 length $l_{2}=15.0 \mathrm{~m}$ to the arrow is equal to the speed $v_{02}=6.659 \mathrm{mps}$. On this section of the hump, the acceleration of the car $a_{2}=0.323 \mathrm{mps}^{2}$, the travel time $t_{2}=2.142 \mathrm{~s}$ and the exit speed of the car from this section $v_{20}=7.351 \mathrm{mps}$ or 26.46 kmph
2.2. The speed of the car entry (initial speed) on the HS2 length $l_{2}=18.633 \mathrm{~m}$ after the arrow is $v_{022}=7.35 \mathrm{mps}$. At the same time, the acceleration of the car $a_{20}=0.2 \mathrm{mps}^{2}$ and this section of the car passes during $t_{20}=2.453 \mathrm{~s}$ with the speed of the car leaving this section $v_{22}=7.84 \mathrm{mps}$ or 28.2 kmph .
3. The first braking position (1BP) of the hump length $l_{1 \mathrm{bp}}=29.0 \mathrm{~m}$ ). The slope of the hump is $\psi_{03}=0.014 \mathrm{rad}$. ( 14 ppm ). Similarly, [15], it was accepted that this section of the hump car passes in three stages: considering the case when the car first passes part of the length of the wheelbase, then it is braked by a car retarder and then it rolls down the remaining length of this retarder. In practice, the braking of the car on the 1BP section of the hump, it is possible that the car retarder is turned on directly when the first wheelset of the front trolley of the car enters. In this case, the section 1TP of the roller coaster car passes in two stages.
3.1. The speed of the entrance of the car (initial speed) to the section of the wheelbase (WB) of the first braking position (1BP) of the hump (to the car moderator) with a length of $13=8.3 \mathrm{~m}$ is equal to $\mathrm{v} 03=7.84 \mathrm{mps}$. On this section of the hump, the acceleration of the car a3 $=0.166 \mathrm{mps}^{2}$, and this section of the car passes in time $\mathrm{t} 3=$ 1.047 s with the speed of the car leaving this section $\mathrm{v} 3=8.014 \mathrm{mps}$ or 28.88 kmph .
3.2. The speed of the entrance of the car (initial speed) to the section 1BP of the hump $(\mathrm{ZB})$ with a length of $13 \mathrm{t}=10.227 \mathrm{~m}$ (the braking path of the car) is equal to $\mathrm{v} 03 \mathrm{t}=$ 8.01 mps . On this section of the hump, during braking $\mathrm{t} 3 \mathrm{t}=1.6 \mathrm{~s}$, the car moves equidistant (acceleration $\mathrm{a} 3 \mathrm{t}=-2.027$ ) $\mathrm{mps}^{2}$ and sliding speed $\mathrm{v} 3 \mathrm{t}=4.77 \mathrm{mps}$ or 17.17 $\mathrm{km} / \mathrm{h}$.
3.3. The speed of the entrance of the car (initial speed) for the remaining length of the 1 BP section of the hump $(\mathrm{FROM}) 13$ from $=10.472 \mathrm{~m}(13$ from $=1 \mathrm{~b} 3-(13+13 \mathrm{~b})=29$ $-(8.3+10.227)=10.472 \mathrm{~m}$, where $\mathrm{lb} 3=29 \mathrm{~m}$ - the entire length of the section 1 BP of the hump) is equal to $v 03$ from $=4.77 \mathrm{mps}$. On this section of the hump with a length of 13 from $=10.472 \mathrm{~m}$ (in Table $1: 102.59 \mathrm{~m}$ ) during t3from $=2.117 \mathrm{~s}$, the car moves equidistant at a3 from $=0.166 \mathrm{mps}^{2}$, the speed of its exit from this section $v_{03 \text { from }}=5.122 \mathrm{mps}$ or $18.44 \mathrm{~km} / \mathrm{h}$.
4. Intermediate section (IN) of the hump length $l_{\text {in }}=41.27 \mathrm{~m}$ (in Table 1: 143.86 m ). The slope of the hump is $\psi_{04}=0.011 \mathrm{rad}$. ( 11 ppm ). It also considers the movement of the car in two stages [15]: before and after the switch.
4.1. The speed of the entrance of the car (initial speed) to the intermediate section (IN) of the hump $14=20.001 \mathrm{~m}$ to the switch is equal to $\mathrm{v} 04=5.122 \mathrm{mps}$. On the section of the roller coaster during the time $t 4=3.721 \mathrm{~s}$, the car moves with an acceleration $\mathrm{a} 4=0.136 \mathrm{mps} 2$, the speed of its exit from this section $\mathrm{v} 4=5.569 \mathrm{mps}$ or $20,3 \mathrm{kmph}$.
4.2. The speed of the entrance of the car (initial speed) to the IN section with a length of $140=21.271 \mathrm{~m}$ after the switch is equal to $\mathrm{v} 042=5.569 \mathrm{mps}$. At the same time, the acceleration of the car a $40=0.13 \mathrm{mps} 2$ and this section of the car passes during $\mathrm{t} 40=$ 3.626 s with the speed of the car leaving this section $v_{42}=6.1 \mathrm{mps}$ or 22.0 kmph .
5. The second braking position (2BP) of the hump length $12 \mathrm{bp}=31.0 \mathrm{~m}$. The slope of the hump is $\psi 05=0.010 \mathrm{rad}$. $(10 \mathrm{ppm})$. Similarly to section 1 BP , section 2BP, the car also passes in three stages [15]: first, the car passes part of the length of the wheelbase, then it is braked by the car retarder and then it rolls down the remaining length of the retarder.
5.1. The speed of the entrance of the car (initial speed) to the section of the wheelbase (WB) 2BP of the hump (up to the car moderator) with a length of $15=10.401 \mathrm{~m}$ is equal to $\mathrm{v} 05=6,1 \mathrm{mps}$. On this section of the hump, the acceleration of the car a $5=$ 0.127 mps 2 , the travel time $\mathrm{t} 5=1.675 \mathrm{~s}$. and the exit speed of the car from this section $\mathrm{v} 5=6.315 \mathrm{~m} / \mathrm{s}$ or 22.73 kmph .
5.2. The speed of the entrance of the car (initial speed) to the section 2BP of the hump (ZB) with a length of $15 \mathrm{~b}=7.458 \mathrm{~m}$ (the braking path of the car) is equal to $\mathrm{v} 05 \mathrm{~b}=$
6.315 mps . On this section of the hump, during braking $\mathrm{t} 5 \mathrm{~b}=1.6 \mathrm{~s}$, the car moves equidistant with acceleration $\mathrm{a} 5 \mathrm{~b}=-2.067 \mathrm{mps} 2$ and sliding speed $\mathrm{v} 5 \mathrm{~b}=3.01 \mathrm{mps}$ or 10.8 kmph .
5.3. The speed of entry of the car (initial speed) for the remaining length of the section $2 \mathrm{BP}($ FROM $) 15$ from $=13,142 \mathrm{~m}(15$ from $=31-(10,401+7,458)=13.142 \mathrm{~m}$, where $\mathrm{lb} 5=31 \mathrm{~m}-$ the entire length of the section 2 BP of the hump) is equal to v 05 from $=$ 3.01 mps . On this section of the hump with a length of 15 from $=13.142 \mathrm{~m}$ during 15 from $=4.027 \mathrm{~s}$, the car moves equidistant with acceleration a5from $=0.127 \mathrm{mps} 2$, the speed of its exit from this section $v 5$ from $=3.518 \mathrm{mps}$ or 12.7 kmph .
6. The switch zone (SZ) with a length of $l_{\mathrm{sz}}=86.69 \mathrm{~m}$. The slope of the hump is $\psi_{06}=0.002$ rad. ( 2 ppm ). Here we consider the movement of the car in four stages: before and after the first switch (arrow), after the second arrow and after the third arrow.
6.1. The speed of the entrance of the car (initial speed) to the section of the NW with a length of $16=16.0 \mathrm{~m}$ to the first arrow is equal to $\mathrm{v} 06=3.518 \mathrm{mps}$. On this section of the hump, the movement of the car, unlike [14], is equidistant at a $6=0.048 \mathrm{mps} 2$, the travel time $\mathrm{t} 6=4.414 \mathrm{~s}$ and the speed of the car's exit from this section $\mathrm{v} 60=3.731$ mps or 13.4 kmph .
6.2. The speed of the entrance of the car (initial speed) to the section of the SZ after the first arrow with a length of $16 \mathrm{~s} 1=25.69 \mathrm{~m}$ is equal to $\mathrm{v} 06 \mathrm{~s} 1=3.731 \mathrm{mps}$. At the same time, the movement of the car is equidistant with acceleration $\mathrm{a} 6 \mathrm{~s} 1=0.041 \mathrm{mps} 2$ and this section of the car passes during t6s $1=6.641 \mathrm{~s}$ with the speed of the car's exit from this section $\mathrm{v} 6 \mathrm{c} 1=4.0 \mathrm{mps}$ or 14.4 kmph .
6.3. 6.3. The speed of the entrance of the car (initial speed) to the section of the SZ after the second arrow with a length of $16 \mathrm{~s} 2=21.0 \mathrm{~m}$ is equal to $\mathrm{v} 06 \mathrm{~s} 2=4.0 \mathrm{mps}$. At the same time, the car moves equidistant with acceleration a6s $2=0.041 \mathrm{mps} 2$ and this section of the car passes during t6s $2=5.11 \mathrm{~s}$ with the speed of the car leaving this section $\mathrm{v} 6 \mathrm{c} 2=4.214 \mathrm{mps}$ or 15.2 kmph .
6.4. The speed of the entrance of the car (initial speed) to the section of the SZ after the third arrow with a length of $l_{6 s 3}=24.0 \mathrm{~m}$ is equal to $v_{0653}=4.214 \mathrm{mps}$. At the same time, the movement of the car is equidistant with acceleration $a_{633}=0.041 \mathrm{mps}^{2}$ and this section of the car passes during $t_{653}=5.545 \mathrm{~s}$ with an exit speed $v_{653}=4.442 \mathrm{mps}$ or 16.0 kmph .
7. The first section of the sorting track (ST1) with a length of $l_{\text {st } 1}=59.18 \mathrm{~m}$. The slope of the hump is $\psi_{07}=0.0016 \mathrm{rad} .(1,6 \mathrm{ppm})$. The speed of entry of the car (initial speed) to this section is $v_{07}=4.442 \mathrm{mps}$. At the same time, the movement of the car, equidistant with acceleration $a_{7}=0.044 \mathrm{mps}$ and this section of the car, passes at a speed of $v_{7}=4.49$ mps or 18.0 kmph during $t_{7}=12.549$.
8. Park mechanized braking position (3BP) humps with a length of $l_{3 \mathrm{bp}}=14.5 \mathrm{~m}$. The slope of the hump is $\psi_{08}=0.0015 \mathrm{rad}$. $(1,5 \mathrm{ppm})$. Unlike sections 1 BP and 2BP, the 3BP section of the car passes in two stages: first, the car passes part of the length of the wheelbase, then it is braked by a car retarder.
8.1. The speed of the entrance of the car (initial speed) to the section of the wheelbase (WB) 3BP of the hump (up to the car moderator) with a length of $18=6.25 \mathrm{~m}$ is equal to $\mathrm{v} 05=4.9 \mathrm{mps}$. On this section of the hump, the acceleration of the car $\mathrm{a} 8=0.041$ mps 2 , the travel time $\mathrm{t} 8=1.246 \mathrm{~s}$ and the exit speed of the car from this section $\mathrm{v} 8=$ 5.04 mps or 18.15 kmph .
8.2. The speed of the entrance of the car (initial speed) to the section 3BP of the hump (ZB) with a length of $l_{8 \mathrm{~b}}=3.965 \mathrm{~m}$ (the braking path of the car) is equal to $v_{08 \mathrm{~b}}=5.04$ mps . On this section of the hump, during braking $t_{8 \mathrm{~b}}=1.0 \mathrm{~s}$, the car moves equidistant with acceleration $a_{8 \mathrm{~b}}=-2.15 \mathrm{mps}^{2}$ and sliding speed $v_{8 \mathrm{~b}}=2.89 \mathrm{mps}$ or 10.4 kmph .
9. The second section of the sorting track (ST2) with a length of $l_{9}=51.285 \mathrm{~m}$. The slope of the hump is $\psi_{09}=0.0006 \mathrm{rad}$. $(0,6 \mathrm{ppm})$. The speed of the entrance of the car to this section $v_{09}=2.89 \mathrm{mps}$. This section of the hump car passes in time $\mathrm{t} 9=16.182 \mathrm{~s}$. In this case, the acceleration and speed of the car are equal to a $9=0.034 \mathrm{mps} 2$ and $\mathrm{v} 9=3.448$ mps or 12.4 kmph . As can be seen, the collision speed of the car "with a group of standing cars" is more than 2 times ( $12,4 \mathrm{kmph}$ ) higher than the permissible ( 5 kmph ) [19]. Hence it is clear that in the sorting park there is a kind of "hard" collision of the car "with a group of standing cars", which is unacceptable. It is for this reason that brake shoes are used in practice in the sorting park.
10. The area of installation of brake shoes of the sorting park (ZBSh). If the brake shoe is installed at a distance of 5 m from the design point (DP), then the car moves equidistant with acceleration $a_{9 \text { sh }}=-1.817 \mathrm{mps}^{2}$ and after $t_{9}=1.88 \mathrm{~s}$, the car stops $v_{9 \text { sh }}=0$ before reaching DP , which is extremely undesirable, since in this case it is necessary to perform additional maneuvering work to eliminate "windows". If the brake shoe is installed at a distance of 3.0 m from the design point (DP), then the car moves equidistant with the same acceleration $a_{9 \text { sh }}=-1.817 \mathrm{mps}^{2}$ and after $t_{9 \text { sh }}=1.35 \mathrm{~s}$ its speed becomes equal to $v_{9 \text { sh }}$ $=0.993 \mathrm{mps}$ or 3.58 kmph , which is less than the permissible ( 5 kmph ) [19, 22]. At the same time, there is a "soft" impact "with a group of standing wagons" on the sorting fleet, which is acceptable.

## 4 Discussion

Now, using the data, we will construct a graphical dependence of the change in the acceleration of the car $a_{k}$ along the length $l_{j}$ of the descent part of the sorting hump when exposed to the force of a tailwind of small magnitude $F_{r \mathrm{rg}}$, taking into account the strength of resistances of all kinds r . (fig. 1).


Fig. 1. Graphical changes in the acceleration of the car along the length of the descent part of the sorting hump, taking into account the strength of the resistance $\mathrm{F}_{\mathrm{r}}$.

From Fig. 1 it is clear that in the braking zones the car moves equidistant, for example, in sections 1BP, 2BP and ZBSh, where linear accelerations have negative values.
Similarly, $a_{k}=f\left(l_{j}\right)$, using the data, it is possible to construct graphical dependencies $t_{k}=f\left(l_{j}\right)$ (Fig. 2) and $v_{k}=f\left(l_{j}\right)$ (Fig. 2).


Fig. 2. Graphical changes in the time of movement of the car along the length of the descent part of the sorting hump, taking into account the strength of the resistance Fr.


Fig. 3. Graphical changes in the rolling speed of the car along the length of the descent part of the sorting hump, taking into account the resistances of the force Fr.

The designations in Fig. 2 and 3 are the same as in Fig. 1.
From Fig. 3 it is clear that in the braking zones there are decreases in the sliding speed of the car, for example, in sections 1BP, 2BP and ZBSh, where linear accelerations have negative values (see Fig. 1).

## 5 Conclusions

1. Based on previously performed studies [1], for the first time, the results of calculations of linear accelerations of a wagon with its equally accelerated and/or equally slow motion on various sections of the sorting hump are presented in tabular form.
2. The analysis of the presented graphical dependences of the travel time and the rolling speed of the car on various sections of the sorting hump made it possible to note that in the case of impact on the car with a load, the projection of the force of a tailwind of small magnitude $F_{r \mathrm{rg}}$, taking into account the strength of resistances of all kinds (medium, arrows, curves, snow and frost) $F_{r}$. the speed of collision of the car "with a group of standing wagons" more than 2 times ( 12.4 kmph ) exceeds the permissible ( 5 kmph ) [1921]. Hence it is clear that in the sorting park there is a "hard" collision of the car "with a
group of standing cars", which is unacceptable. It is for this reason that brake shoes are used in practice in the sorting park. If the brake shoe is installed at a distance of 3.0 m from the design point, the car will reach "a group of standing cars" in the sorting park in 1.35 seconds at a speed of 3.58 kmph less than the permissible ( 5 kmph ) [19-21]. At the same time, there is a "soft" impact "with a group of standing wagons" on the sorting fleet, which is acceptable.

## References

1. J. Prokop, Sh. Myojin, Memoirs of the Faculty of Engineering, Okayama University 27(2), 59-71 (1993)
2. C. Zhang, Y. Wei, G. Xiao, Z. Wang, J. Fu, Second Intern. Conf. on Transportation and Traffic Studies 285-290. (2000) https://doi.org/10.1061/40503(277)45
3. M. Bardossy, Analysis of Hump Operation at a Railroad Classification Yard in Proceedings of the 5th International Conference on Simulation and Modeling Methodologies, Technologies and Applications (SIMULTECH-2015) 493-500. https://doi.org/10.5220/0005546704930500
4. N. Boysen, S. Emde, M. Fliedner, OR Spectrum January 38(1), 207-233 (2016)
5. Chenxu Lu, Jin Shi, Advances in Structural Engineering (2019) https://doi.org/10.1177/1369433219870573.
6. C.T. Dick, J.R. Dirnberger, Advancing the science of yard design and operations with the CSX hump yard simulation system in Proceedings of the 2014 Joint Rail Conference, 1-10 (2014)
7. S.O. Bantyukova, Eastern-European Journal of Enterprise Technologies 3(75) (2015)
8. Operational and Technical Requirements for the Hump Yards (Warsaw, 2018).
9. V. Bobrovskyi, D. Kozachenko, A. Dorosh, E. Demchenko, T. Bolvanovska, A. Kolesnik, Transport Problems 11(1), 147-155 (2016) https://doi.org/10.20858/tp.2016.11.1.14
10. S. Djabborov, S. Saidivaliev, B. Abdullaev, R. Abdullaev, R. Tursunkhodzaeva, Neuroquantology 20(12), 3025-3036 (2022) https://doi.org/10.14704/nq.2022.20.12.nq77301
11. Kh.T. Turanov, A.A. Gordienko, Sh.U. Saidivaliev, International Journal of Advanced Studies 8(4), 122 - 136 (2018) https://doi.org/10.12731/2227-930X-2018-4-122-136. ISSN 0236-1914
12. D. Kozachenko, V. Bobrovskyi, Y. Demchenko, Journal of Modern Transportation 26(3), 189199 (2018) https://doi.org/10.1007/s40534-018-0161-2
13. Kh.T. Turanov, A.A. Gordienko, Transp. Urals. 2(57), 3-8 (2018) https://doi.org/10.20291/1815-9400-2018-2-3-8. ISSN 1815-9400.
14. O. Polach, Wear 258(1), 992-1000 (2005)
15. K. Turanov, A. Gordienko, S. Saidivaliev, S. Djabborov, E3S Web of Conferences 164, 03038 (2020) https://doi.org/10.1051/e3sconf/202016403038
16. K. Turanov, A. Gordienko, S. Saidivaliev, S. Djabborov, E3S Web of Conferences 164, 03041 (2020) https://doi.org/10.1051/e3sconf/202016403041
17. K. Turanov, A. Gordienko, S. Saidivaliev, S. Djabborov, K. Djalilov, Kinematic Characteristics of the Car Movement from the Top to the Calculation Point of the Marshalling Hump in Murgul V., Pukhkal V. (eds) International Scientific Conference Energy Management of Municipal Facilities and Sustainable Energy Technologies EMMFT 2019. EMMFT 2019. Advances in Intelligent Systems and Computing 1258 (2021) https://doi.org/10.1007/978-3-030-57450-529
18. K.T. Turanov, S.U. Saidivaliev, D.I. Ilesaliev, Structural integrity and life 20(2), 143-147 (2020)
19. Sh. Saidivaliev, R. Bozorov, E. Shermatov, E3S Web of Conferences 264, 05008 (2021) https://doi.org/10.1051/e3sconf/202126405008
20. Kh. Turanov, E. Timukhina, A. Gordienko, TransSiberia 1115, 703-716 (2020) https://doi.org/10.1007/978-3-030-37916-2_69
21. A.G. Kotenko, S.B. Sattorov, V.P. Nehoroshkov, K.M. Timuhin, Journal of Physics: Conference Series 2131(3), 032102 (2021). https://doi.org/10.1088/1742-6596/2131/3/032102
22. D. Ilesaliev, J. Kobulov, R. Tursunkhodjaeva, M. Tashmatova, Lecture Notes in Networks and Systems 510, 829-840 (2023) https://doi.org/10.1007/978-3-031-11051-1_85

[^0]:    * Corresponding author: shuxratxoja@mail.ru

